

## Chapter 14 Inductor Design

- 14.1 Filter inductor design constraints
- 14.2 A step-by-step design procedure
- 14.3 Multiple-winding magnetics design using the  $K_g$  method
- 14.4 Examples
- 14.5 Summary of key points

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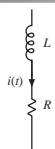
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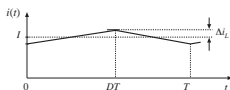
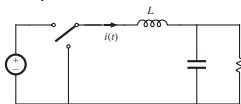
### 14.1 Filter inductor design constraints



Objective:  
Design inductor having a given inductance  $L$ , which carries worst-case current  $I_{max}$  without saturating, and which has a given winding resistance  $R$ , or, equivalently, exhibits a worst-case copper loss of

$$P_{cu} = I_{rms}^2 R$$

**Example:** filter inductor in CCM buck converter




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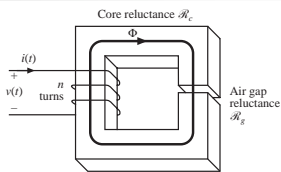
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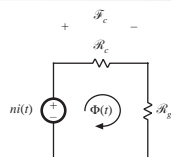
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### Assumed filter inductor geometry



$$\mathcal{R}_c = \frac{\ell_c}{\mu_r \mu_0 A_c}$$

$$\mathcal{R}_g = \frac{\ell_g}{\mu_0 A_c}$$



Solve magnetic circuit:  
 $ni = \Phi (\mathcal{R}_c + \mathcal{R}_g)$   
Usually  $\mathcal{R}_c \ll \mathcal{R}_g$  and hence  
 $ni = \Phi \mathcal{R}_g$

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### 14.1.1 Constraint: maximum flux density

Given a peak winding current  $I_{max}$ , it is desired to operate the core flux density at a peak value  $B_{max}$ . The value of  $B_{max}$  is chosen to be less than the worst-case saturation flux density  $B_{sat}$  of the core material. From solution of magnetic circuit:

$$ni = BA_c \mathcal{R}_g$$

Let  $I = I_{max}$  and  $B = B_{max}$  :

$$nI_{max} = B_{max} A_c \mathcal{R}_g = B_{max} \frac{\ell_g}{\mu_0}$$

This is constraint #1. The turns ratio  $n$  and air gap length  $\ell_g$  are unknown.

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### 14.1.2 Constraint: inductance

Must obtain specified inductance  $L$ . We know that the inductance is

$$L = \frac{n^2}{\mathcal{R}_g} = \frac{\mu_0 A_c n^2}{\ell_g}$$

This is constraint #2. The turns ratio  $n$ , core area  $A_c$ , and air gap length  $\ell_g$  are unknown.

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### 14.1.3 Constraint: winding area

Wire must fit through core window (i.e., hole in center of core)

Total area of copper in window:

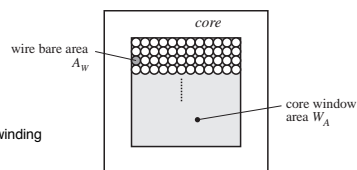
$$nA_w$$

Area available for winding conductors:

$$K_u W_A$$

Third design constraint:

$$K_u W_A \geq nA_w$$




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## The window utilization factor $K_{u1}$ also called the "fill factor"

$K_u$  is the fraction of the core window area that is filled by copper

Mechanisms that cause  $K_u$  to be less than 1:

- Round wire does not pack perfectly, which reduces  $K_u$  by a factor of 0.7 to 0.55 depending on winding technique
- Insulation reduces  $K_u$  by a factor of 0.95 to 0.65, depending on wire size and type of insulation
- Bobbin uses some window area
- Additional insulation may be required between windings

Typical values of  $K_u$ :

- 0.5 for simple low-voltage inductor
- 0.25 to 0.3 for off-line transformer
- 0.05 to 0.2 for high-voltage transformer (multiple kV)
- 0.65 for low-voltage foil-winding inductor

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## 14.1.4 Winding resistance

The resistance of the winding is

$$R = \rho \frac{\ell_b}{A_w}$$

where  $\rho$  is the resistivity of the conductor material,  $\ell_b$  is the length of the wire, and  $A_w$  is the wire bare area. The resistivity of copper at room temperature is  $1.724 \cdot 10^{-6} \Omega \cdot \text{cm}$ . The length of the wire comprising an  $n$ -turn winding can be expressed as

$$\ell_b = n (MLT)$$

where  $(MLT)$  is the mean-length-per-turn of the winding. The mean-length-per-turn is a function of the core geometry. The above equations can be combined to obtain the fourth constraint:

$$R = \rho \frac{n (MLT)}{A_w}$$

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## 14.1.5 The core geometrical constant $K_g$

The four constraints:

$$n I_{max} = B_{max} A_c \mathcal{R}_g = B_{max} \frac{\ell_g}{\mu_0} \quad L = \frac{n^2}{\mathcal{R}_g} = \frac{\mu_0 A_c n^2}{\ell_g}$$

$$K_u W_A \geq n A_w$$

$$R = \rho \frac{n (MLT)}{A_w}$$

These equations involve the quantities

$A_c$ ,  $W_A$ , and  $MLT$ , which are functions of the core geometry,

$I_{max}$ ,  $B_{max}$ ,  $\mu_0$ ,  $L$ ,  $K_u$ ,  $R$ , and  $\rho$ , which are given specifications or other known quantities, and

$n$ ,  $\ell_g$ , and  $A_w$ , which are unknowns.

Eliminate the three unknowns, leading to a single equation involving the remaining quantities.

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## Core geometrical constant $K_g$

Elimination of  $n$ ,  $l_g$ , and  $A_w$  leads to

$$\frac{A_c^2 W_A}{(MLT)} \geq \frac{\rho L^2 I_{max}^2}{B_{max}^2 R K_u}$$

- Right-hand side: specifications or other known quantities
- Left-hand side: function of only core geometry

So we must choose a core whose geometry satisfies the above equation.

The core geometrical constant  $K_g$  is defined as

$$K_g = \frac{A_c^2 W_A}{(MLT)}$$

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## Discussion

$$K_g = \frac{A_c^2 W_A}{(MLT)} \geq \frac{\rho L^2 I_{max}^2}{B_{max}^2 R K_u}$$

$K_g$  is a figure-of-merit that describes the effective electrical size of magnetic cores, in applications where the following quantities are specified:

- Copper loss
- Maximum flux density

How specifications affect the core size:

A smaller core can be used by increasing

$B_{max} \Rightarrow$  use core material having higher  $B_{sat}$

$R \Rightarrow$  allow more copper loss

How the core geometry affects electrical capabilities:

A larger  $K_g$  can be obtained by increase of

$A_c \Rightarrow$  more iron core material, or

$W_A \Rightarrow$  larger window and more copper

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## 14.2 A step-by-step procedure

The following quantities are specified, using the units noted:

Wire resistivity	$\rho$	( $\Omega$ -cm)
Peak winding current	$I_{max}$	(A)
Inductance	$L$	(H)
Winding resistance	$R$	( $\Omega$ )
Winding fill factor	$K_u$	
Core maximum flux density	$B_{max}$	(T)

The core dimensions are expressed in cm:

Core cross-sectional area	$A_c$	(cm <sup>2</sup> )
Core window area	$W_A$	(cm <sup>2</sup> )
Mean length per turn	$MLT$	(cm)

The use of centimeters rather than meters requires that appropriate factors be added to the design equations.

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### Determine core size

$$K_g \geq \frac{\rho L^2 I_{max}^2}{B_{max}^2 R K_u} 10^8 \quad (\text{cm}^5)$$

Choose a core which is large enough to satisfy this inequality  
(see Appendix D for magnetics design tables).

Note the values of  $A_w$ ,  $W_A$ , and  $MLT$  for this core.

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### Determine air gap length

$$\ell_g = \frac{\mu_0 L I_{max}^2}{B_{max}^2 A_c} 10^4 \quad (\text{m})$$

with  $A_c$  expressed in  $\text{cm}^2$ .  $\mu_0 = 4\pi \cdot 10^{-7} \text{H/m}$ .

The air gap length is given in meters.

The value expressed above is approximate, and neglects fringing flux and other nonidealities.

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### $A_L$

Core manufacturers sell gapped cores. Rather than specifying the air gap length, the equivalent quantity  $A_L$  is used.

$A_L$  is equal to the inductance, in mH, obtained with a winding of 1000 turns.

When  $A_L$  is specified, it is the core manufacturer's responsibility to obtain the correct gap length.

The required  $A_L$  is given by:

$$A_L = \frac{10 B_{max}^2 A_c^2}{L I_{max}^2} \quad (\text{mH}/1000 \text{ turns})$$

Units:  
 $A_c$   $\text{cm}^2$ ,  
 $L$  Henries,  
 $B_{max}$  Tesla.

$$L = A_L n^2 10^{-9} \quad (\text{Henries})$$

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Determine number of turns  $n$

$$n = \frac{LI_{max}}{B_{max}A_c} 10^4$$

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Evaluate wire size

$$A_w \leq \frac{K_g W_A}{n} \text{ (cm}^2\text{)}$$

Select wire with bare copper area  $A_w$  less than or equal to this value. An American Wire Gauge table is included in Appendix D.

As a check, the winding resistance can be computed:

$$R = \frac{\rho n (MLT)}{A_w} \text{ (}\Omega\text{)}$$

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### 14.3 Multiple-winding magnetics design using the $K_g$ method

The  $K_g$  design method can be extended to multiple-winding magnetic elements such as transformers and coupled inductors.

This method is applicable when

- Copper loss dominates the total loss (i.e. core loss is ignored), or
- The maximum flux density  $B_{max}$  is a specification rather than a quantity to be optimized

To do this, we must

- Find how to allocate the window area between the windings
- Generalize the step-by-step design procedure

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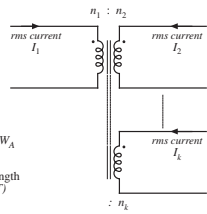
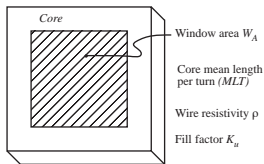
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### 14.3.1 Window area allocation

**Given:** application with  $k$  windings having known rms currents and desired turns ratios

$$\frac{v_1(t)}{n_1} = \frac{v_2(t)}{n_2} = \dots = \frac{v_k(t)}{n_k}$$



**Q:** how should the window area  $W_A$  be allocated among the windings?

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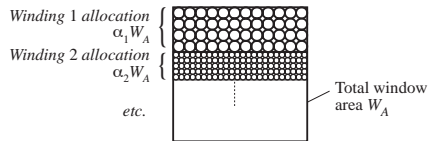
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### Allocation of winding area



$$0 < \alpha_j < 1$$

$$\alpha_1 + \alpha_2 + \dots + \alpha_k = 1$$

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### Copper loss in winding $j$

Copper loss (not accounting for proximity loss) is

$$P_{cu,j} = I_j^2 R_j$$

Resistance of winding  $j$  is

$$R_j = \rho \frac{\ell_j}{A_{w,j}}$$

with

$$\ell_j = n_j (\text{MLT})$$

length of wire, winding  $j$

$$A_{w,j} = \frac{W_A K_u \alpha_j}{n_j}$$

wire area, winding  $j$

Hence

$$R_j = \rho \frac{n_j^2 (\text{MLT})}{W_A K_u \alpha_j}$$

$$P_{cu,j} = \frac{n_j^2 I_j^2 \rho (\text{MLT})}{W_A K_u \alpha_j}$$

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## Total copper loss of transformer

Sum previous expression over all windings:

$$P_{cu,tot} = P_{cu,1} + P_{cu,2} + \dots + P_{cu,k} = \frac{\rho (MLT)}{W_A K_w} \sum_{j=1}^k \left( \frac{n_j^2 I_j^2}{\alpha_j} \right)$$

Need to select values for  $\alpha_1, \alpha_2, \dots, \alpha_k$  such that the total copper loss is minimized

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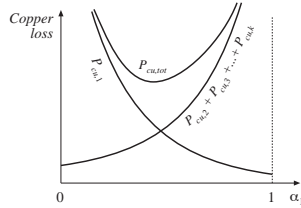
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## Variation of copper losses with $\alpha_1$



**For  $\alpha_1 = 0$ :** wire of winding 1 has zero area.  $P_{cu,1}$  tends to infinity

**For  $\alpha_1 = 1$ :** wires of remaining windings have zero area. Their copper losses tend to infinity

There is a choice of  $\alpha_1$  that minimizes the total copper loss

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## Method of Lagrange multipliers to minimize total copper loss

Minimize the function

$$P_{cu,tot} = P_{cu,1} + P_{cu,2} + \dots + P_{cu,k} = \frac{\rho (MLT)}{W_A K_w} \sum_{j=1}^k \left( \frac{n_j^2 I_j^2}{\alpha_j} \right)$$

subject to the constraint

$$\alpha_1 + \alpha_2 + \dots + \alpha_k = 1$$

Define the function

$$f(\alpha_1, \alpha_2, \dots, \alpha_k, \xi) = P_{cu,tot}(\alpha_1, \alpha_2, \dots, \alpha_k) + \xi g(\alpha_1, \alpha_2, \dots, \alpha_k)$$

where

$$g(\alpha_1, \alpha_2, \dots, \alpha_k) = 1 - \sum_{j=1}^k \alpha_j$$

is the constraint that must equal zero

and  $\xi$  is the Lagrange multiplier

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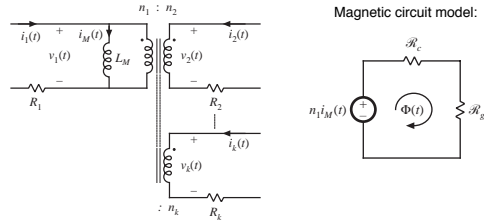
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### 14.3.2 Coupled inductor design constraints

Consider now the design of a coupled inductor having  $k$  windings. We want to obtain a specified value of magnetizing inductance, with specified turns ratios and total copper loss.




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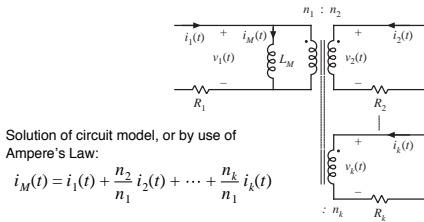
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### Relationship between magnetizing current and winding currents



Solution of circuit model, or by use of Ampere's Law:

$$i_M(t) = i_1(t) + \frac{n_2}{n_1} i_2(t) + \dots + \frac{n_k}{n_1} i_k(t)$$

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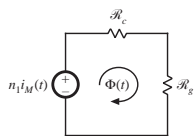
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### Solution of magnetic circuit model: Obtain desired maximum flux density



Assume that gap reluctance is much larger than core reluctance:

$$n_1 i_M(t) = B(t) A_c \mathcal{R}_g$$

Design so that the maximum flux density  $B_{max}$  is equal to a specified value (that is less than the saturation flux density  $B_{sat}$ ).  $B_{max}$  is related to the maximum magnetizing current according to

$$n_1 I_{M,max} = B_{max} A_c \mathcal{R}_g = B_{max} \frac{\ell_g}{\mu_0}$$

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## Obtain specified magnetizing inductance

By the usual methods, we can solve for the value of the magnetizing inductance  $L_M$  (referred to the primary winding):

$$L_M = \frac{n_1^2}{\mathcal{R}_g} = n_1^2 \frac{\mu_0 A_c}{\ell_g}$$

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## Copper loss

Allocate window area as described in Section 14.3.1. As shown in that section, the total copper loss is then given by

$$P_{cu} = \frac{\rho(MLT)n_1^2 I_{tot}^2}{W_A K_u}$$

with 
$$I_{tot} = \sum_{j=1}^k \frac{n_j}{n_1} I_j$$

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## Eliminate unknowns and solve for $K_g$

Eliminate the unknowns  $\ell_g$  and  $n_1$ :

$$P_{cu} = \frac{\rho(MLT)L_M^2 I_{tot}^2 J_{M,max}^2}{B_{max}^2 A_c^2 W_A K_u}$$

Rearrange equation so that terms that involve core geometry are on RHS while specifications are on LHS:

$$\frac{A_c^2 W_A}{(MLT)} = \frac{\rho L_M^2 I_{tot}^2 J_{M,max}^2}{B_{max}^2 K_u P_{cu}}$$

The left-hand side is the same  $K_g$  as in single-winding inductor design. Must select a core that satisfies

$$K_g \geq \frac{\rho L_M^2 I_{tot}^2 J_{M,max}^2}{B_{max}^2 K_u P_{cu}}$$

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### 3. Determine number of turns

For winding 1:

$$n_1 = \frac{L_M I_{M,max}}{B_{max} A_c} 10^4$$

For other windings, use the desired turns ratios:

$$n_2 = \left( \frac{n_2}{n_1} \right) n_1$$

$$n_3 = \left( \frac{n_3}{n_1} \right) n_1$$

$$\vdots$$

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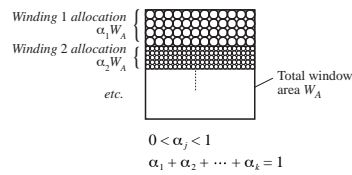
### 4. Evaluate fraction of window area allocated to each winding

$$\alpha_1 = \frac{n_1 I_1}{n_1 I_{tot}}$$

$$\alpha_2 = \frac{n_2 I_2}{n_1 I_{tot}}$$

$$\vdots$$

$$\alpha_k = \frac{n_k I_k}{n_1 I_{tot}}$$




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### 5. Evaluate wire sizes

$$A_{w1} \leq \frac{\alpha_1 K_w W_A}{n_1}$$

$$A_{w2} \leq \frac{\alpha_2 K_w W_A}{n_2}$$

$$\vdots$$

See American Wire Gauge (AWG) table at end of Appendix D.

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## 14.4 Examples

### 14.4.1 Coupled Inductor for a Two-Output Forward Converter

### 14.4.2 CCM Flyback Transformer

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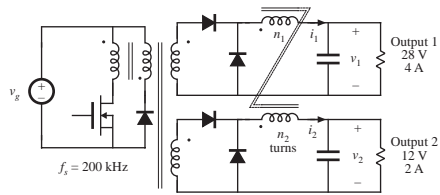
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### 14.4.1 Coupled Inductor for a Two-Output Forward Converter



The two filter inductors can share the same core because their applied voltage waveforms are proportional. Select turns ratio  $n_2/n_1$  approximately equal to  $v_2/v_1 = 12/28$ .

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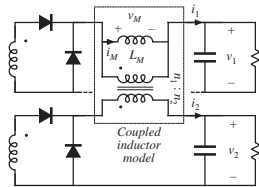
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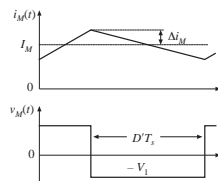
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## Coupled inductor model and waveforms



Secondary-side circuit, with coupled inductor model



Magnetizing current and voltage waveforms.  $i_M(t)$  is the sum of the winding currents  $i_1(t) + i_2(t)$ .

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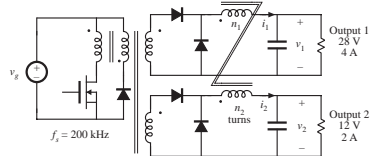
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## Nominal full-load operating point

Design for CCM operation with  
 $D = 0.35$   
 $\Delta i_M = 20\%$  of  $I_M$   
 $f_s = 200$  kHz



DC component of magnetizing current is

$$I_M = I_1 + \frac{n_2}{n_1} I_2$$

$$= (4 \text{ A}) + \frac{12}{28} (2 \text{ A})$$

$$= 4.86 \text{ A}$$

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## Magnetizing current ripple

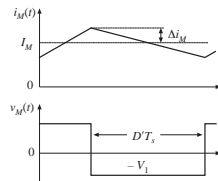
$$\Delta i_M = \frac{V_1 D T_s}{2L_M}$$

To obtain  
 $\Delta i_M = 20\%$  of  $I_M$   
 choose

$$L_M = \frac{V_1 D T_s}{2\Delta i_M}$$

$$= \frac{(28 \text{ V})(1 - 0.35)(5 \text{ } \mu\text{s})}{2(4.86 \text{ A})(20\%)}$$

$$= 47 \text{ } \mu\text{H}$$



This leads to a peak magnetizing current (referred to winding 1) of  
 $I_{M,max} = I_M + \Delta i_M = 5.83 \text{ A}$

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## RMS winding currents

Since the winding current ripples are small, the rms values of the winding currents are nearly equal to their dc components:

$$I_1 = 4 \text{ A} \qquad I_2 = 2 \text{ A}$$

Hence the sum of the rms winding currents, referred to the primary, is

$$I_{tot} = I_1 + \frac{n_2}{n_1} I_2 = 4.86 \text{ A}$$

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## Evaluate $K_g$

The following engineering choices are made:

- Allow 0.75 W of total copper loss (a small core having thermal resistance of less than 40 °C/W then would have a temperature rise of less than 30 °C)
- Operate the core at  $B_{max} = 0.25$  T (which is less than the ferrite saturation flux density of 0.3 or 0.5 T)
- Use fill factor  $K_f = 0.4$  (a reasonable estimate for a low-voltage inductor with multiple windings)

Evaluate  $K_g$ :

$$K_g \geq \frac{(1.724 \cdot 10^{-6} \Omega - \text{cm})(47 \mu\text{H})^2(4.86 \text{ A})^2(5.83 \text{ A})^2}{(0.25 \text{ T})^2(0.75 \text{ W})(0.4)} 10^8$$

$$= 16 \cdot 10^{-3} \text{ cm}^5$$

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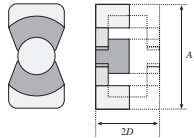
## Select core

It is decided to use a ferrite PQ core. From Appendix D, the smallest PQ core having  $K_g \geq 16 \cdot 10^{-3} \text{ cm}^5$  is the PQ 20/16, with  $K_g = 22.4 \cdot 10^{-3} \text{ cm}^5$ . The data for this core are:

$$A_c = 0.62 \text{ cm}^2$$

$$W_A = 0.256 \text{ cm}^2$$

$$MLT = 4.4 \text{ cm}$$




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## Air gap length

$$l_g = \frac{\mu_0 L_M I_{M,max}^2}{B_{max}^2 A_c} 10^4$$

$$= \frac{(4\pi \cdot 10^{-7} \text{ H/m})(47 \mu\text{H})(5.83 \text{ A})^2}{(0.25 \text{ T})^2(0.62 \text{ cm}^2)} 10^4$$

$$= 0.52 \text{ mm}$$

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## Specifications

Input voltage	$V_g = 200\text{V}$
Output (full load)	20 V at 5 A
Switching frequency	150 kHz
Magnetizing current ripple	20% of dc magnetizing current
Duty cycle	$D = 0.4$
Turns ratio	$n_2/n_1 = 0.15$
Copper loss	1.5 W
Fill factor	$K_u = 0.3$
Maximum flux density	$B_{max} = 0.25\text{ T}$

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## Basic converter calculations

Components of magnetizing current, referred to primary:

$$I_M = \left(\frac{n_2}{n_1}\right) \frac{1}{D} \frac{V}{R} = 1.25\text{ A}$$

$$\Delta i_M = (20\%) I_M = 0.25\text{ A}$$

$$I_{M,max} = I_M + \Delta i_M = 1.5\text{ A}$$

Choose magnetizing inductance:

$$L_M = \frac{V_g D T_s}{2 \Delta i_M} = 1.07\text{ mH}$$

RMS winding currents:

$$I_1 = I_M \sqrt{D} \sqrt{1 + \frac{1}{3} \left(\frac{\Delta i_M}{I_M}\right)^2} = 0.796\text{ A}$$

$$I_2 = \frac{n_1}{n_2} I_M \sqrt{D} \sqrt{1 + \frac{1}{3} \left(\frac{\Delta i_M}{I_M}\right)^2} = 6.50\text{ A}$$

$$I_{tot} = I_1 + \frac{n_2}{n_1} I_2 = 1.77\text{ A}$$

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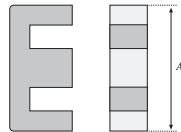
## Choose core size

$$K_g \geq \frac{\rho L_M^2 I_{tot}^2 I_{M,max}^2}{B_{max}^2 P_{cu} K_u} 10^8$$

$$= \frac{(1.724 \cdot 10^{-6} \Omega \cdot \text{cm}) (1.07 \cdot 10^{-3} \text{ H})^2 (1.77 \text{ A})^2 (1.5 \text{ A})^2}{(0.25 \text{ T})^2 (1.5 \text{ W})(0.3)} 10^8$$

$$= 0.049 \text{ cm}^5$$

The smallest EE core that satisfies this inequality (Appendix D) is the EE30.




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