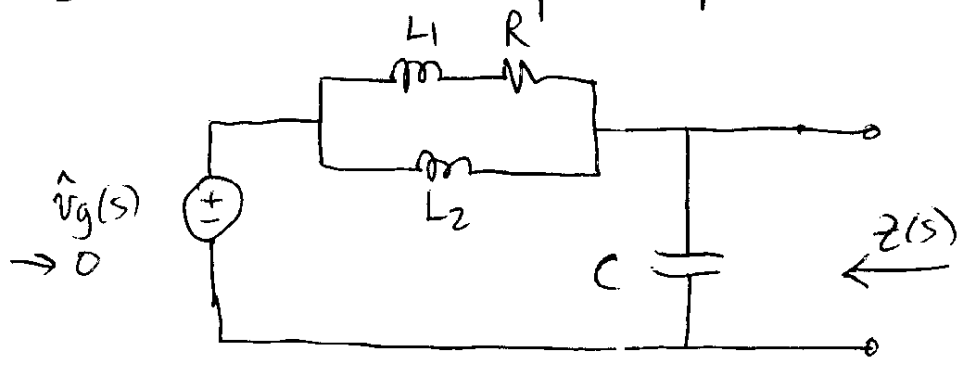


Employing the  $n$ -extra element theorem when the dc value of the asymptote is zero

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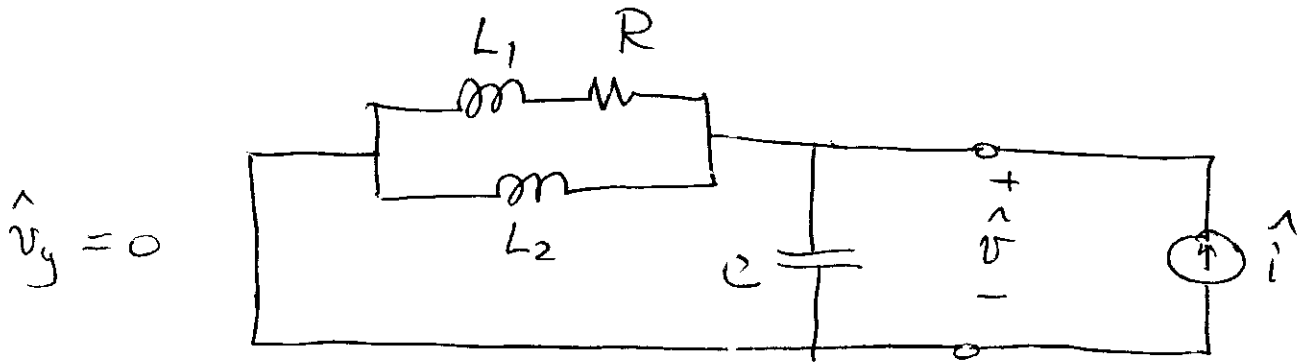
Sometimes, the dc value of the transfer function is not a nonzero, finite value. This happens whenever the low-frequency asymptote has a nonzero slope. In the power electronics field, this is nearly always the case for impedances (as long as parasitic loss elements are not modeled), because we do not want the dc or 60 Hz current to flow through a lossy resistive element.

For example, consider the output impedance  $Z(s)$  of the damped input filter shown below:



(2)

To measure this impedance, we would set  $\hat{v}_g \Rightarrow 0$ , then inject a current  $\hat{i}$  and measure the induced voltage  $\hat{v}$ :



$$Z(s) = \frac{\hat{v}}{\hat{i}} \Big|_{\hat{v}_g = 0}$$

So  $Z(s)$  is the transfer function from  $\hat{i}$  to  $\hat{v}$ .

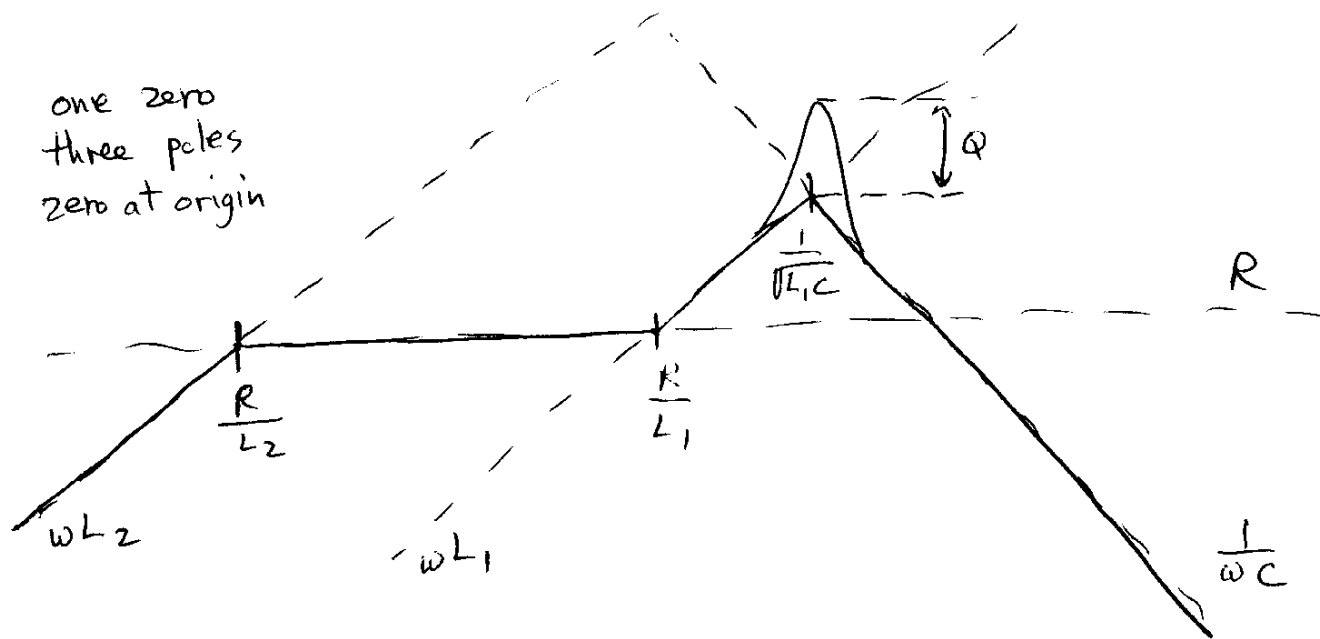
If we try to use the n-extra element theorem in its basic form, we obtain a dc value of zero, so that

$$Z(s) = 0 \cdot \frac{\text{zeros}}{\text{poles}}$$

This isn't going to work. We need to use a form that contains one or more inverted poles or zeroes, so that  $Z(s)$  is referred to a non-zero midband gain.

③

As an aside, let's construct  $Z(s)$  using the algebra on the graph technique, for the case where  $L_2 \gg L_1$ :



It looks like we could express  $Z(s)$  using an inverted pole at  $\frac{R}{L_2}$ , a midband asymptote of  $R$ , a regular zero at  $\frac{R}{L_1}$ , and regular complex poles at  $\frac{1}{\sqrt{LC}}$ , as follows:

$$Z(s) \approx R \frac{\left(1 + \frac{sL_1}{R}\right)}{\left(1 + \frac{R}{sL_2}\right) \left(1 + \frac{s}{\omega_0} + \left(\frac{s}{\omega_0}\right)^2\right)}$$

with  $\omega_0 = \frac{1}{\sqrt{LC}}$

$Q$  is perhaps less obvious, although it can be approximated, using the  $\frac{R}{L_1}$  zero, as  $Q \approx \frac{1}{R} \sqrt{\frac{L_1}{C}}$

(4)

If the approximate analysis of the previous page is good enough, then our work is done. But if we want to optimize the design of the input filter (making  $L_2$  no larger than necessary), then we can't make the approximation  $L_2 \gg L_1$ . So we need to work out the actual  $Z(s)$ . In higher-order input filters having several damped L-C sections, the need for developing an accurate expression for  $Z(s)$  becomes even more acute.

So we need to generalize the u-extra-element theorem to handle inverted poles and zeroes. This can be done by generalizing the ideas of "low frequency state" and "high frequency state" of a reactive element, as follows;

Replace the terms

"low-frequency state" with "normal state"

"high-frequency state" with "abnormal state"

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The normal state of each inductor or capacitor can be chosen to be either a short circuit or an open circuit. The "reference gain" of the transfer function (previously called the "dc gain") is equal to the value of the transfer function when all inductors and capacitors are set to their normal states. The transfer function is then written in the form

$$G(s) = (\text{reference gain}) \frac{\text{(regular and/or inverted zeros)}}{\text{(regular and/or inverted poles)}}$$

"numerator and denominator polynomials"

The numerator and denominator polynomials may now contain terms with negative powers of  $s$ . We use the usual method to find the polynomial coefficients, except that "low-frequency state" is replaced by "normal state", "high-frequency state" is replaced by "abnormal state", and inverted terms are used whenever the normal state coincides with the high-frequency state, as follows:

$$\frac{sL}{R} \rightarrow \frac{R}{sL}, \quad sRC \rightarrow \frac{1}{sRC}$$

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## Impedance example

The low-frequency asymptote of  $Z(s)$  tends to zero because of  $L_2$ . So let's invert the  $sL_2$  terms. If we let

$$\begin{aligned}
 sL_2 &\rightarrow \text{open circuit} \\
 sL_1 &\rightarrow \text{short circuit} \\
 \frac{1}{sC} &\rightarrow \text{open circuit}
 \end{aligned}$$

then we obtain  $Z \rightarrow R$

Therefore, let's define the normal and abnormal states as follows:

<u>Element</u>	<u>normal state</u>	<u>abnormal state</u>
$L_1$	short (dc)	open (HF)
$L_2$	open (HF)	short (dc)
$C$	open (dc)	short (HF)

We can write  $Z(s)$  in the following form:

$$Z(s) = R \frac{1 + \left( \frac{sL_1}{R_h} + sC R_i + \frac{R_j}{sL_2} \right)}{1 + \left( \frac{sL_1}{R_a} + sC R_b + \frac{R_c}{sL_2} \right) + \left( sC R_b \frac{sL_1}{R_d} + sC R_b \frac{R_e}{sL_2} + \frac{R_c}{sL_2} \frac{sL_1}{R_f} \right)}$$

(Recall from p. 3 that  $Z(s)$  contains three poles, one zero, and a zero at the origin)

The above form for  $Z(s)$  is written in the usual (almost) manner, with three poles and one zero, except that the  $\frac{sL_2}{R_x}$  terms are inverted, and  $Z(s)$  is referenced to

the midband gain  $R$ . The denominator polynomial is 3<sup>rd</sup> order, but contains  $s^1, s^0, s^1,$  and  $s^2$  terms.

The coefficients are found in the usual manner:

Denominator terms

set all independent

sources to zero!

$\hat{v}_g = 0$ ,  $\hat{i} = 0$   
short      open

$R_a$ : resistance seen by  $L_1$  when  $L_2$  and  $C$  are set to their normal states

$L_2 \rightarrow$  open  
 $C \rightarrow$  open

$R_a = \infty$

$R_b$ : resistance seen by  $C$  when  $L_1$  and  $L_2$  are set to their normal states

$L_1 \rightarrow$  short  
 $L_2 \rightarrow$  open

$R_b = R$

$R_c$ : resistance seen by  $L_2$  when  $L_1$  and  $C$  are set to their normal states

$L_1 \rightarrow$  short  
 $C \rightarrow$  open

$R_c = R$

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$R_d$ : resistance seen by  $L_1$  when  $C = \text{abnormal state (short)}$  and  $L_2 = \text{normal state (open)}$   
 $R_d = R$

$R_e$ : resistance seen by  $L_2$  when  $C = \text{abnormal state (short)}$  and  $L_1 = \text{normal state (short)}$   
 $R_e = 0$

$R_f$ : resistance seen by  $L_1$  when  $L_2 = \text{abnormal state (short)}$  and  $C = \text{normal state (open)}$   
 $R_f = R$

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Zeros: In the presence of  $\hat{i}$ , inject at the  $L_1, L_2$ , or  $C$  port such that  $\hat{v} \xrightarrow{\text{null}} 0$

$R_h$ : resistance seen by  $L_1$  when  $C$  and  $L_2$  are set to their normal states and  $\hat{v} \xrightarrow{\text{null}} 0$   
 $C \rightarrow \text{open} \quad L_2 \rightarrow \text{open}$

$$R_h = R$$

(9)

$R_i$ : resistance seen by  $C$  when  $L_1$  and  $L_2$  are set to their normal states and  $\hat{v} \rightarrow 0$   
 $L_1 \rightarrow \text{short}$      $L_2 \rightarrow \text{open}$   
 $\text{null}$

$$R_i = 0$$

$R_j$ : resistance seen by  $L_2$  when  $L_1$  and  $C$  are set to their normal states and  $\hat{v} \rightarrow 0$   
 $L_1 \rightarrow \text{short}$      $C \rightarrow \text{open}$   
 $\text{null}$

$$R_j = 0$$

So

$$Z(s) = R \frac{1 + \frac{sL_1}{R}}{1 + sRC + \frac{R}{sL_2} + s^2 L_1 C + \frac{sL_1}{sL_2}}$$

To write in the usual form, multiply by  $\frac{\left(\frac{sL_2}{R}\right)}{\left(\frac{sL_2}{R}\right)}$

$$Z(s) = sL_2 \frac{\left(1 + \frac{sL_1}{R}\right)}{\left(1 + \frac{s(L_1+L_2)}{R} + s^2 L_2 C + \frac{s^3 L_1 L_2 C}{R}\right)}$$