Lab Overview

In this lab assignment, you will do the following:

- Add an LCD and a serial EEPROM to your hardware. Implement a memory mapped I/O interface to the LCD and a bit-banged interface to the EEPROM. Use C pointers to access the LCD as a memory-mapped peripheral.
- Write device drivers for the LCD and EEPROM.
- Write assembly and C programs to implement a user interface and perform user tasks.
- Gain experience in code integration.
- Continue learning how to use SDCC (and perhaps an IDE or makefiles).
- Continue learning about the ARM architecture.

Students must work individually and develop their own original and unique hardware/software.

The signature due date for this lab assignment is Friday, April 6, 2018 (Part 1 Required Elements) and Friday, April 13, 2018 (Part 2 Required/Supplemental/Challenge Elements). Software files must be submitted by 4pm on the signoff day to be considered on time.

The submission due date for this lab is 11:59pm Saturday, April 14, 2018.

The cutoff date for this lab is Saturday, April 21, 2018.

This lab is weighted as ~20% of your course grade.

Note: The LCD interface must be implemented with the 8051 hardware. The I2C interface may be implemented with either the 8051 or the ARM hardware.

Required elements are necessary in order to meet the requirements for the lab. Supplemental/challenge elements of the lab assignment may be completed by the student to qualify for a higher grade, but they do not have to be completed to successfully meet the requirements for the lab.

The highest possible grade an ECEN 5613 student can earn on this assignment without completing any of the supplemental elements is a 'B'. ECEN 5613 students will have to complete the supplemental elements and show differentiation in the quality of their work in order to compete for the highest grades. To avoid any late penalties, ECEN 5613 students must obtain a TA’s signature on their work by the specified signature due dates for required and supplemental elements.

If you are up for an engineering challenge and want to learn more, then attempt the optional challenge(s). You do not need to complete optional elements in order to get a signature; however, completing optional elements with good results will help your work stand out. Students must prioritize work on required elements and supplemental elements over challenge elements.

All items on the signoff sheet must be completed to get a signature, but partial credit is given for incomplete labs. Note that receiving a signature on the signoff sheet does not mean that your work is eligible for any particular grade; it merely indicates that you have completed the work at an acceptable level.

NOTE: The quality of your user interfaces and demo will impact your score on the lab. Your goal should be to ensure that the user has a successful and positive experience with your software. Your code should handle error conditions gracefully (e.g. user input values outside the allowed range). Top scores are reserved for those students who submit outstanding implementations, including coding style.
Lab Details

1. Review the homework assignments associated with this lab.

2. Review the data sheets for the Optrex DMC 20434 LCD and the SED1278F (or Hitachi HD44780U) LCD controller. Review the document "SED1278F Technical Manual Errata".

   Refer to the LCD Guide ("Adding an LCD (with an HD44780 LCD controller) to your board") available on the course web site for further ideas and information on interfacing to the LCD module. It contains some very important notes, including one regarding errors in the LCD data sheet.

3. [Required Element] Devise a way to securely mount the LCD and properly connect all of the data lines to your board. It may take you a little time to devise a good physical interface, so don’t wait too long before getting started. Wire can be used to easily attach the LCD to your board without requiring any drilling (remember the previous warnings against drilling holes in the PCB).

   **Data Lines:** Most LCDs will have only 14 pins. LCDs with a backlight will have 16 pins, with two for the backlight. One option for connecting data lines is to use a 14-pin strip header or SIPP wire wrap socket. You may also attach the LCD through a ribbon cable to a 14- or 16-pin DIP socket on your board. A sturdy data line connection using a strip header can make it easy to mount the LCD.

4. [Required Element] Design and implement your LCD circuit. Your LCD must be memory mapped in the address space reserved for peripherals (this is an example of memory mapped I/O), and will be accessible using the MOVX instruction (and via a pointer variable in C). The LCD contrast (V_{EE}) can sometimes be grounded, but you probably need to use a potentiometer or resistor divider to control the contrast so that you can see characters on the screen. The LCD in the parts kit has 14 pins/lines which must be connected.

   The eight data signals on the LCD must be connected to the data lines on Port 0 of the 8051. Ensure that the E signal on the LCD is high only when reading from or writing to the LCD.

**NOTE:** When asking the TA’s and instructor for help with your program, be sure to attach all required/relevant files to your e-mail. Attach the commented source files (.c, .h), and the listing and memory usage files (for SDCC, the .rst, .mem, and .map files). If your question involves external peripherals (even NVSRAM), you will also need to attach a PDF or sketch of your schematic.
5. [Required Element\textsuperscript{1}] Implement an LCD device driver with the following C functions:
   
   - // Name: lcdinit()
     // Description: Initializes the LCD (see Figure 25 on page 212 of the HD44780U data sheet).
     void lcdinit()
   
   - // Name: lcdbusywait()
     // Description: Polls the LCD busy flag. Function does not return until the LCD controller is ready to accept another command.
     void lcdbusywait()
   
   - // Name: lcdgotoaddr()
     // Description: Sets the cursor to the specified LCD DDRAM address. Should call lcdbusywait().
     void lcdgotoaddr(unsigned char addr)
   
   - // Name: lcdgotoxy()
     // Description: Sets the cursor to the LCD DDRAM address corresponding to the specified row and column. Location (0,0) is the top left corner of the LCD screen. Must call lcdgotoaddr().
     void lcdgotoxy(unsigned char row, unsigned char column)
   
   - // Name: lcdputch()
     // Description: Writes the specified character to the current LCD cursor position. Should call lcdbusywait().
     void lcdputch(char cc)
   
   - // Name: lcdputstr()
     // Description: Writes the specified null-terminated string to the LCD starting at the current LCD cursor position. Automatically wraps long strings to the next LCD line after the right edge of the display screen has been reached. Must call lcdputch().
     void lcdputstr(char *ss)
   
   - // Name: lcdclear()
     // Description: Clears the LCD using the HD44780 Clear display instruction.
     void lcdclear()

   **NOTE:** I prefer you to write your own code for these routines. However, a variety of LCD routines and libraries suitable for SDCC are available on the web. You may use these libraries as long as your code contains clear documentation of how you obtained, utilized and/or modified them. Each of your code files must have a file header which identifies all authors of the code. (You already know this is the standing expectation in this class with regard to borrowed code.) **You must have a complete understanding of how all the code works.**

6. [Required Element\textsuperscript{1}] Write a simple program that uses your LCD driver to prove that the required functions are implemented correctly. Choose the sequence carefully so that it is easy for the TA to see that each function did its job correctly during the demonstration. This program is just test code and does not need to be completely robust, as long as it adequately demonstrates the functionality of each of the LCD functions above.

7. [Required Element\textsuperscript{1}] Using a logic analyzer, prove that your LCD control signal timing is correct. Show the timing between the E, RS, R/W*, and data signals as measured at your LCD interface.

   - A logic analyzer screen capture or a simple hand sketch of these timing relationships and values must be turned in with your lab, along with your timing analysis.

   You should also be able to prove that the LCD E control signal goes high only when the LCD is being accessed. You can verify this by running code which does not access the LCD and by triggering the logic analyzer on E going high. If E goes high during this test, then your implementation is incorrect. You may also be able to test this by using Paulmon2.
8. Read the EEPROM Guide "Adding an NM24C04 (or NM24C16) EEPROM to your board", available on the course web site. It has ideas and information on interfacing to the I²C EEPROM.

Read the data sheet for the serial EEPROM included in your parts kit (e.g. Microchip 24LC16 or Fairchild-National Semiconductor NM24C16). You may also want to read Fairchild Application Note AN-794.

[Optional, but recommended] Review Microchip app notes AN536, AN572, AN614 and AN709.

9. [Required Element] Design and implement your EEPROM circuit. Your EEPROM should be connected to two unused port pins. Note that since you are connecting to the EEPROM using port pins, the EEPROM does not consume any processor address space.

NOTE: In the next step, your EEPROM driver code may require use of specific port pins

10. [Required Element] Implement an EEPROM I²C device driver with the ability to write and read a byte at any EEPROM I²C address using function calls from C. The underlying drivers may be in assembly if you wish, but the functions must be accessible from C. It does not matter what you name the functions. For example, you might implement the following two functions.

```c
int eebytew(addr, databyte)  // write byte, returns status
int eebyter(addr)            // read byte, returns data or status
```

NOTE: A variety of I²C routines and libraries written in C are available on the web – a quick web search would be beneficial. You may use these libraries as long as your code contains clear documentation of how you obtained, utilized and/or modified them. (You already know this is the standing expectation in this class with regard to borrowed code.)

11. [Part 1 Required Element] Verify that you can write data to and read data from the EEPROM using your I²C device driver and verify the stored data is correct after cycling power. Your code should not ignore ACK’s during I2C transactions.

12. [Part 1 Required Element] Use a logic analyzer to prove that your byte write function sends the correct signals and has the correct I²C timing. Note that the LogicPort logic analyzer has an I²C interpreter that you might find useful as you debug your I²C bus transactions.

- **A simple hand sketch or a logic analyzer screen capture of these timing relationships and values must be turned in with your lab, along with your timing analysis.**

13. [Optional] Use the I²C triggering program on the [Agilent 54622D] oscilloscope to trigger on a write or read frame on the bus. Display SCL and SDA on the oscilloscope screen and verify that the transaction is for the address you intended. Verify that your rise and fall times fall within the limits given in the I²C specification. Alternatively, use a logic analyzer to trigger on a bus transaction.
14. [Part 1 Required Element\(^1\)]

**NOTE:** For this lab, as much of your code as possible should be integrated – this will provide experience with integrating much functionality into a single program, and will also reduce signoff times since only a single program must be stored in the flash memory on your processor. Your demo and submission should be one well-integrated program, but the program can be modularized and consist of multiple code and header files.

Provide a well-designed menu on the PC terminal emulator screen which allows the user to:

- **Write Byte:** Enter an EEPROM address and a byte data value in hex. If the address and data are valid, store the data into the EEPROM. The program must allow any hex value from 0x00 to 0xFF to be programmed into any location in the EEPROM. Do not make the user type in "0x" before the address or data hex value.

- **Read Byte:** Enter an EEPROM address in hex. If the EEPROM address is valid, display on the PC screen in hex the contents of the EEPROM address, using the format "AAA: DD". Do not make the user type in "0x" before the address hex value.

- **Hex Dump:** Enter a start address and end address in hex. If the entered values are valid, read the contents of the EEPROM from the start address to the end address and display the data on the PC screen in hexadecimal, with a maximum of 16 bytes of data per line, in the following format: AAA: DD DD DD DD DD DD DD DD DD DD DD DD DD DD DD DD DD DD DD DD

  This format is similar to what you see when using the device programmer or when dumping memory contents using PAULMON2, where AAA is the starting address (in hex) for each block of 16 data values DD (in hex). The first memory cell in the EEPROM is address 0x0000. You should be able to leverage code from Lab #3. Do not make the user type in "0x" before the address hex values.

- **Reset EEPROM:** Provide a function named `eereset()` in your EEPROM I²C device driver:

  ```c
  // Name: eereset()
  // Description: Performs a software reset of the I2C EEPROM using an
  // algorithm that conforms to Microchip application note AN709.
  void eereset()
  ```

  Use a logic analyzer to prove that `eereset` sends the correct sequence and has the correct I²C timing.

  Show the trace on the logic analyzer to the TA during signoff. You do **not** need to print/submit the trace with your report.

  Demonstrate that you understand application note AN709 and the functionality of the `eereset` code during your sign-off.

The user must be able to execute menu items in any order (the program should not include any dependencies on the order in which a user selects menu items).

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\(^1\) Required elements are necessary in order to meet the requirements for the lab. Supplemental, optional, and challenge elements of the lab assignment may be completed by the student to qualify for a higher grade, but they do not have to be completed to successfully meet the minimum requirements for the lab.
15. [Part 1 Required Element]¹

Provide a well-designed menu on the PC terminal emulator screen with the following options:

- **DDRAM Dump**: Reads the entire contents of the LCD DDRAM and displays it in hex on the PC screen in a clean and logical format.

- **CGRAM Dump**: Reads the entire contents of the LCD CGRAM and displays it in hex on the PC screen in a clean and logical format.

- **Create Custom Character**: Design and implement C routines which allow the creation of custom LCD characters using CGRAM. Implement the following function:

  // Name: lcdcreatechar()
  // Description: Function to create a 5x8 pixel custom character with
  // character code ccode (0<=ccode<=7) using the row values given in
  // the 8-byte array row_vals[].
  void lcdcreatechar(unsigned char ccode, unsigned char row_vals[])  

Provide a way for users to enter and display their own custom characters. A good custom character generation routine user interface should:

(a) accept values from the user representing the pixel pattern for each row of the custom character (the design can choose to allow either strings of bits or hex values representing each row of the character)

(b) display the current state to the user on the terminal screen after each row is entered

As part of your demo, show that you have created some fun logo using custom characters. For example, you could use several custom characters grouped together to create a pixel map of the CU logo.
16. [Part 2 Required Element]:

**NOTE:** The code for this element must be integrated with the previous LCD code above. Your demo and submission should be one well-integrated program.

- In the bottom right corner of the LCD, continuously display the elapsed time since your program started running using the format "MM:SS.S", where MM is the number of elapsed minutes and SS.S represents the seconds to one-tenth of a second accuracy. For example, 5.1 seconds would be displayed as "00:05.1" and 64.3 seconds would be displayed as “01:04.3”.
- Provide **Clock** menu options to stop the elapsed time clock, to restart the clock, and to reset the clock back to "00:00.0".

**NOTE:** Make sure that the cursor location is correctly stored before and restored after any ISRs.

**NOTE:** If using SDCC, read the "interrupt" sections of the SDCC user manual carefully, and remember the correct use of 'volatile' and 'critical'. Be careful when using variables from within the context of an ISR. This includes any functions that your ISR calls. Do not use printf/sprintf in an ISR (note that printf and sprintf share code).

**NOTE:** This supplemental element is an addition to the previous required LCD element. **The required and supplemental code must be integrated together.** The elapsed timer must work correctly while simultaneously allowing all the menu options in the previous C program to work correctly.

**NOTE:** If you get this supplemental element signed off, don't turn in separate versions of code for both the required LCD part and the supplemental LCD part - just submit one integrated version.

17. [Part 2 Supplemental Element]: (8051 or MSP432)

**NOTE:** If this element is implemented on the same system as your previous I2C code, the code for this element should be integrated into the previous I2C programs above and your demo and submission should be one well-integrated program.

- Read the PCF8574 I2C I/O expander data sheets and application notes available from the course website. Integrate the chip into your embedded system, sharing the I2C bus with the EEPROM, and prove that you can configure some of its I/O pins to work as inputs and other pins to work simultaneously as outputs (at least one input and one output). Your parts kit already included a 16-pin wire wrap socket that could be used with the I2C expander chip. You can purchase another wire wrap socket if necessary.

Choose some easy mechanism to demonstrate your I/O expander. For instance, read the state of one PCF8574 pin that is configured as an input, then invert that value and write it back out to the output pin on the PCF8574. Use the interrupt signal from the I/O expander to notify the processor when the input changes. Make sure you choose appropriate triggering (level- or edge-) for the interrupt on the processor. Provide a basic software driver that allows you to configure the pins individually as inputs or outputs, and also to check the status of the pins and to write to the pins that are outputs. Remember to use a bit mask in software when interacting with specific pins on the chip.

Note: Your choices of input and output pins can be hard coded for this element; you don’t need to create a user interface that allows the user to arbitrarily select which pins are inputs and outputs.
18. **[Part 2 Supplemental Element\(^1\)]: (8051 or MSP432)**

Explore the SPI protocol and the use of a SPI controller.

Obtain a discrete ADC or DAC device that has a SPI interface and connect it to the 8051 or MSP432 Launchpad board. Configure the processor to communicate with the device using the processor’s integrated SPI controller and demonstrate that SPI device’s capabilities. Be careful not to exceed the max voltage level specification for the input pins.

Use a logic analyzer to study a SPI transaction and understand the protocol. Show the trace on the logic analyzer to the TA during signoff. You do **not** need to print/submit the trace with your report.

During your signoff, be able to compare SPI and I\(^2\)C and discuss each protocol’s relative advantages.

19. **[Part 2 Supplemental Element\(^1\)]: (MSP432)**

Continue learning about the ARM architecture and the MSP432:

a) Demonstrate the ability to use the MSP432 debugger. Be able to discuss some of its capabilities.

b) Demonstrate that you can successfully build and execute code that demonstrates at least two additional MSP432 features that you did not previously demonstrate earlier in the semester. Include an interrupt service routine in your code for Lab #4.

c) Explain your key learnings to the TA’s.
20. **[Challenge]: (MSP432)**

Explore the MSP432’s DMA controller. Demonstrate one or more of the following:

For this challenge, you may need to refer to several different information sources including example code and the following documents:


   a) Use DMA with the MSP432 ADC. Demonstrate the ability to have DMA transfer multiple samples from the ADC into memory.

   b) Provide a compile time switch to either process the samples in the ADC interrupt handler or by using DMA.

   c) Demonstrate the ability to do a memory block copy using DMA. Copy a block from flash to SRAM or copy a block from SRAM to SRAM.

During your signoff, be able to explain why DMA is important in an embedded system, including any impact on performance and power in the system.

21. **[Challenge]: (MSP432 and 8051)**

Explore level translation circuits.

Obtain a voltage level translator (level shifter) IC and use it to properly interface 5V signals from the 8051 board with lower voltage signals from the ARM board. Demonstrate proper operation of the circuits.

As one idea, the MSP432 Launchpad has two GPIO pushbuttons. Configure the system such that if either of the buttons is pushed, it generates a GPIO interrupt on the MSP432 and causes the MSP432 to exchange some piece of information with the 8051 board. Perhaps a value from the MSP432 is sent to the 8051 to be written to the LCD or into the EEPROM, and perhaps a value is sent from the 8051 to the MSP432 to control the state of one of the MSP432 LED’s.

During your signoff, be able to discuss the technical need for voltage level shifters and explain any different options you found for level translator solutions.
Submission Questions

22. [Part 2 Required Element¹] As part of your submission, provide answers to the following:

a) What operating system (including revision) did you use for your code development?

b) What compiler(s) (including revision) did you use?

c) What exactly (include name/revision if appropriate) did you use to build your code (an IDE, make/makefile, or command line)?

d) Did you install and use any other software tools to complete your lab assignment?

e) Did you experience any problems with any of the software tools? If so, describe the problems.

NOTE: Make copies of your code, SPLD code, and schematic files and save them as an archive. You will need to submit the Lab #4 files electronically at the end of the semester.

Submission Instructions

Instructions: Print your name and sign the honor code pledge on the signoff sheet. Turn in a scan of the signed form, the items in the checklist below, and the answers to any applicable lab questions in order to receive credit for your work. No cover sheet please.

In addition to the items listed on the signoff checklist, be sure to review the lab for additional requirements for submission. Submit all items electronically via Desire2Learn (D2L, https://learn.colorado.edu), to reduce paper usage.

- Scan of signed and dated signoff sheet as the top sheet (No cover sheet please)
- Scan of timing diagrams and analyses for the LCD and EEPROM interfaces
- PDF of full copy of complete and accurate schematic of acceptable quality (all old/new components shown). Include programmable logic source code (e.g. .PLD file for the SPLD).
- Full copy of fully, neatly, clearly commented source code (including C and header files, and .RST, .MEM, and .MAP files). Ensure your code is neat and easy to read, and that each file has detailed header comments that identify the author and any leveraged code the file contains - there will be deductions if this information is not provided for all files. If you submit a PDF of your code in order to improve its appearance, you must also submit the original source code files as well.
- A short lab write-up with a description of any significant new learnings and the answers to submission questions regarding software environment and tools. If you used a makefile, submit a copy of that makefile.
- Answers to submission questions regarding software environment and tools.

Make copies of your code, SPLD code, and schematic files and save them as an archive. You will need to submit all the lab files electronically at the end of the semester.
You will need to obtain the signature of your TA on the following items in order to receive credit for your lab assignment. Signatures are due by Friday, April 6, 2018 (Part 1 Required Elements) and Friday, April 13, 2018 (Part 2 Required/Supplemental/Challenge Elements).

Print your name below, sign the honor code pledge, circle your course number, and then demonstrate your working hardware & firmware in order to obtain the necessary signatures.

Student Name: ______________________________________

Honor Code Pledge: "On my honor, as a University of Colorado student, I have neither given nor received unauthorized assistance on this work. I have clearly acknowledged work that is not my own."

Student Signature: _____________________________

Signoff Checklist

Part 1 Required Elements

- Pins and signals labeled and decoupling capacitors present on board
- LCD functional, C code for basic LCD routines functional
- LCD control signal timing meets specifications (diagram)
- Serial EEPROM functional, contents present after power cycle
- C code for EEPROM functional, I²C timing correct
- EEPROM eereset() functional and correct
- Support for custom LCD characters, fun logo
- LCD Display, Clear, and Hex/DDRAM/CGRAM dumps
- Support for custom LCD characters, fun logo

Part 2 Required and Supplemental Elements

- Elapsed time display (accurate 1 second resolution)
- Elapsed time stop, restart, reset to "00:00.0":
- Good integration with previous LCD code, all functions work with no irregularities
- SPI interface
- PCF8574 I²C I/O Expander
- TI MSP432 ARM code development

TA signature and date

FOR TA/INSTRUCTOR USE ONLY

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TA/Instructor Comments □ □ □

Optional Challenges: DMA, Level Translation